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Constraining the WMAP9 bispectrum and trispectrum with needlets

Donough Regan, Mateja Gosenca, and David Seery

Astronomy Centre, University of Sussex, Brighton BN1 9QH, United Kingdom

We develop a needlet approach to estimate the amplitude of general (including non-separable) bispectra and trispectra in the cosmic microwave background, and apply this to the WMAP 9-year data. We obtain estimates for the ‘orthogonal’ bispectrum mode, yielding results which are consistent with the WMAP 7-year data. We do not observe the frequency-dependence suggested by the WMAP team’s analysis of the 9-year data. We present 1-σ constraints on the ‘local’ trispectrum shape \( g_{\text{NL}} / 10^5 = -4.1 \pm 2.3 \) for the ‘c1’ equilateral model \( g_{\text{loc}} / 10^6 = -0.8 \pm 2.9 \), and the constant model \( g_{\text{NL}}^\text{const} / 10^6 = -0.2 \pm 1.8 \), together with a 95% confidence-level upper bound on the multifield local parameter \( \tau_{\text{NL}} < 22000 \). We estimate the bias on these parameters produced by point sources. The techniques developed in this paper should prove useful for other datasets such as Planck.

I. INTRODUCTION

The study of primordial non-Gaussianity is now a precision science, making it increasingly important to develop general, effective and efficient estimators (for a review see, for example, Refs. [1] [2]). Fergusson, Shellard and collaborators developed a formalism using a ‘modal’ or ‘partial-wave’ expansion [3–6] which enabled non-separable bi- and trispectrum shapes to be analysed[7] and applied this technology to a version of the KSW estimator [7]. In Ref. [8] an alternative approach was developed which allowed an arbitrary estimator to be coupled to the partial-wave decomposition. This enables the benefits of a particular estimator to be exploited while retaining the ability to detect \( n \)-point functions of arbitrary shape. For example, wavelet-based estimators are efficient detectors of point sources [9]. Ref. [8] implemented such a wavelet-based estimator.

In this paper we make use of a similar approach to couple the partial-wave expansion to a needlet-based estimator. Needlets are a particular class of spherical wavelets which are designed to be localized in both real-space and frequency, and possess properties which make them attractive for CMB analysis. First, they do not require any tangent-plane approximation [10]. Second, unlike general wavelets, needlets are asymptotically uncorrelated in frequency. Therefore, assuming Gaussianity, the coefficients of a needlet decomposition may be treated as independent, identically-distributed random variables at high frequency. This makes them useful as diagnostics of non-Gaussianity.

Needlets were first applied to CMB data by Pietrobon et al. [11] and subsequently used to study primordial non-Gaussianity by a number of authors [10] [12]–[17]. In this paper we make use of Mexican needlets, which were discussed mathematically by Geller & Mayeli [18] and first applied to CMB analysis by Scodeller et al. [19]. These can give a close approximation to the Spherical Mexican Hat wavelet, but decorrelate more rapidly with increasing frequency. We will use them to develop a nearly optimal estimator for both the three- and four-point functions of the CMB, and use it to obtain the first estimates of the bias on the four-point function due to point sources, assuming a simple constant-flux model. In addition to its application to primordial non-Gaussianity, the four-point function estimator can be adapted to study CMB lensing. It could also be used to study perturbations generated by cosmic strings, for which the trispectrum is expected to be larger than the bispectrum [20].

Summary. In §II–III we summarize the use of partial-wave decompositions of arbitrary bi- and trispectra. We describe the construction of cubic and quartic needlet estimators and explain how to calculate optimal constraints. In §IV we apply this methodology to the 9-year WMAP data. Our bispectrum analysis yields results which are consistent in frequency. This disagrees with the analysis by the WMAP team, which suggested mild tension between the \( V \)- and \( W \)-band constraints for the orthogonal mode. We quote constraints for four trispectrum modes: two local shapes (\( g_{\text{NL}}^\text{loc} \) and \( \tau_{\text{NL}}^\text{loc} \)), the constant shape, and the ‘c1’ equilateral shape. Our constraints for \( g_{\text{NL}}^\text{loc} \) are in agreement with the optimal constraints given by Sekiguchi & Sugiyama [21] on the basis of WMAP9 data. In addition we give constraints on the bias induced by points sources for each of the trispectrum modes. In §V we present our conclusions.

II. CMB BISPECTRUM WITH NEEDLETS

To fix notation, we briefly recall some key steps in the decomposition of an arbitrary bispectrum into ‘modes’ or partial waves. For more details we refer to the original literature [3] [4].

1 For the purposes of this paper, a function \( f(k_1, k_2, \cdots, k_n) \) is separable if it can be written as a sum of terms of the form \( f_1(k_1) f_2(k_2) \cdots f_n(k_n) \).
CMB bispectrum. Consider the primordial gravitational potential \( \Phi \), which is related to the curvature perturbation on uniform density hypersurfaces \( \zeta \) by \( \Phi = 3\zeta/5 \). Denoting the spectrum and bispectrum of \( \Phi \) by \( P_\Phi(k) \) and \( B_\Phi(k_1, k_2, k_3) \), and using the basis of orthogonal polynomials \( q_n(k) \) introduced by Fergusson, Liguori & Shellard [3], it is possible to decompose \( B_\Phi \) into this basis by writing

\[
S_\Phi^{(loc)}(k_1, k_2, k_3) \equiv \frac{B_\Phi(k_1, k_2, k_3)}{2(P_\Phi(k_1)P_\Phi(k_2) + P_\Phi(k_1)P_\Phi(k_3) + P_\Phi(k_2)P_\Phi(k_3))} = \sum_{prq} a_{prq}^Q q_p(k_1)q_r(k_2)q_q(k_3).
\]

(1)

where bracketed indices are symmetrized with weight unity. The quantity \( S_\Phi^{(loc)} \) is referred to as the shape. Where \( B_\Phi \) is given by the local model, the shape is independent of the wavenumbers \( k_i \) and corresponds to the amplitude \( f_{NL} \). For convenience we represent unique triplets \((p,r,s)\) using a multi-index \( n \) and define \( Q_n \equiv q_p(k_1)q_r(k_2)q_q(k_3) \). Then the coefficients of the expansion \( a_n^Q \) are obtained by computing

\[
a_n^Q = \sum_m \langle S_\Phi^{(loc)} , Q_m \rangle G_m^{-1}
\]

(2)

where \( G_{mn} = \langle Q_m, Q_n \rangle \), and \( \langle f, g \rangle \) represents the inner product

\[
\langle f, g \rangle \equiv \int_V dv f(k_1, k_2, k_3)g(k_1, k_2, k_3)\omega(k_1, k_2, k_3).
\]

(3)

In this equation \( dv \) is an element of volume on the integration domain \( V \) (defined by the triangle condition, \( 2\max(k_1, k_2, k_3) \leq k_1 + k_2 + k_3 \)), and \( \omega \) is a weight function which can be adjusted to suit our convenience. To obtain a good approximation for \( S_\Phi^{(loc)} \) we find that it is necessary to use \( \sim 100 \) of the \( Q_n \).

Eq. (1) gives the CMB bispectrum

\[
b_{l_1l_2l_3} = \sum_{n=(p,r,s)} 6a_n^Q \int dx \, x^2 \, \bar{q}_p^{(2)}(x)\bar{q}_r^{(-1)}(x)\bar{q}_s^{(-1)}(x) = \sum_{n} a_n^Q b_{l_1l_2l_3}^{(n)}
\]

(4)

where the functions \( \bar{q}_p^{(2)} \) and \( \bar{q}_p^{(-1)} \) are defined by

\[
\bar{q}_p^{(2)}(x) \equiv \frac{2\pi}{\Delta_l(k)j_l(kx)}, \quad \text{and} \quad \bar{q}_p^{(-1)}(x) \equiv \frac{2\pi}{\Delta_l(k)j_l(kx)},
\]

(5)

and \( b_{l_1l_2l_3}^{(n)} \) is understood to be defined by equation (4). In these formulae, \( j_l(kx) \) represents the spherical bessel function of order \( l \) and \( \Delta_l(k) \) represents the CMB transfer function used to map from primordial times to the surface of last scattering. We compute \( \Delta_l(k) \) by solving the collisional Boltzmann equations using CAMB [22].

Eq. (4) represents the CMB bispectrum \( b_{l_1l_2l_3} \) using the coefficients \( a_n^Q \) which determine the primordial bispectrum \( B_\Phi \), and an explicit integration \( \int dx \, x^2 \cdots \) (the ‘line-of-sight’ integral) which appears in \( b_{l_1l_2l_3}^{(n)} \). Under some circumstances it may also be possible to decompose this integral in terms of the basis functions \( Q_n \) [8]. Choosing a normalization for future convenience, this yields

\[
s_{l_1l_2l_3}^{(n)} = \frac{2(l_1+1)\times(2l_2+1)\times(2l_3+1)^{1/6}}{\sqrt{C_{l_1}C_{l_2}C_{l_3}}} \sum_m \Gamma_{nm}Q_m(l_1, l_2, l_3) = \sum_m \Gamma_{nm}Q_m(l_1, l_2, l_3).
\]

(6)

where the first equality is a definition of \( s_{l_1l_2l_3}^{(n)} \). For a fixed number of \( Q_n \), it need not happen that \( \Gamma_{nm} \) is a good approximation. Even in cases where a sufficiently good approximation can be obtained this may require more \( Q_n \) than are needed for \( S_\Phi^{(loc)} \). However, where it applies, the advantage of \( \Gamma_{nm} \) is that the line-of-sight integral is absorbed in the transfer matrix \( \Gamma_{nm} \), which need only be calculated once for each choice of cosmology, represented by the transfer function \( \Delta_l(k) \). An explicit expression for \( \Gamma_{nm} \) was given in Ref. [8]. We will return to the question of whether Eq. (6) is applicable when discussing the trispectrum in [11].

In conclusion, given the coefficients of the primordial decomposition \( a_n^Q \), we may either (a) use Eq. (4) to evaluate the CMB bispectrum directly, or (b) use the transfer matrix to give the coefficients of the CMB shape \( a_n^Q = \sum_m \Gamma_{nm}a_m^Q \), from which the CMB bispectrum can be reconstructed using

\[
s_{l_1l_2l_3} \equiv \sum_n a_n^Q s_{l_1l_2l_3}^{(n)} = \sum_n a_n^Q Q_n(l_1, l_2, l_3).
\]

(7)
Simulating the CMB bispectrum. Now suppose we fix some primordial bispectrum $B(k_1, k_2, k_3)$ and include a component of this with amplitude $f_{NL}^B$, in the gravitational potential $\Phi$, so that $B_{\Phi}(k_1, k_2, k_3) \geq f_{NL}^B B(k_1, k_2, k_3)$. The symbol ‘$\supset$’ indicates that $B_{\Phi}$ contains this contribution among others. Note that $f_{NL}^B$ is the amplitude of the fixed bispectrum $B(k_1, k_2, k_3)$ and therefore does not agree with the traditional $f_{NL}$ parameter defined by Komatsu & Spergel unless $B(k_1, k_2, k_3)$ is the conventionally-normalized local bispectrum. In this paper we always denote the Komatsu & Spergel parameter by $f_{NL}$. Our objective is to estimate $f_{NL}^B$ from the data.

In order to compute the error associated with our estimator it will be necessary to obtain its variance on an ensemble of maps containing a bispectrum corresponding to $B_{\Phi}$, and for that purpose we require a suite of simulated maps with appropriate statistical properties. For a Gaussian map we could generate an appropriate ensemble by making a multipole decomposition $\delta T(\hat{n})/T = \sum_{lm} a_{lm} Y_{lm}(\hat{n})$, drawing the coefficients $a_{lm}$ from a Gaussian distribution. To account for the bispectrum $B_{\Phi}$ we must instead set $a_{lm} = a^G_{lm} + f_{NL}^B a^B_{lm}$, with $a^G_{lm}$ a dominant, Gaussian contribution and $a^B_{lm}$ a non-Gaussian correction chosen to reproduce bispectrum $B(k_1, k_2, k_3)$. A prescription for choosing $a^B_{lm}$ was given by Fergusson, Shellard & Liguori [3],

$$a^B_{lm} = \frac{1}{6} \sum_{l_2,l_3,m_2,m_3} b_{l_2l_3l_2m_2m_3} a^G_{l_2m_2} a^G_{l_3m_3} C_{l_2} C_{l_3},$$

where $a^G_{l_2l_3}$ is the complex conjugate of $a^G_{l_2l_3}$. In what follows we denote quantities which include the bispectrum $B$ by the superscript ‘$B$’. Using the expansion of the CMB bispectrum $b_{l_2l_3l_3}$ in terms of the primordial coefficients $a^G_{lm}$ given by Eq. (4), it follows that $a^B_{lm}$ can be written

$$a^B_{lm} = \sum_n a^G_{lm} \int dx x^2 \int d\hat{n} Y_{lm}(\hat{n}) \left(\tilde{Y}_{\alpha}^G(x, \hat{n}) \tilde{M}_\alpha^{-1} \tilde{M}_p^{-1} \tilde{Y}_{\beta}^G(x, \hat{n})\right),$$

where $\tilde{M}_p^{-1} \tilde{M}_p = \sum_{lm} \tilde{q}_m^{-1} x a^G_{lm} Y_{lm}(\hat{n})/C_l$. Alternatively we may use the CMB decomposition (7) with the result $a^B_{lm} = \sum_n a^G_{lm} a^B_{ln}$, where

$$a^B_{lm} = \frac{1}{6} \sqrt{C_l} \int d\hat{n} Y_{lm}(\hat{n}) g_p \left(\frac{l}{l_{\text{max}}} \right) M_p^G(\hat{n}) M_p^G(\hat{n}),$$

and the weighted maps $M_p^G(\hat{n})$ are defined by $M_p^G(\hat{n}) = \sum_{lm} q_p(l/l_{\text{max}}) a^G_{lm} Y_{lm}(\hat{n})/((2l + 1)^{1/6} \sqrt{C_l})$. We shall employ this latter expansion in this paper.

In Fig. [1] we plot the simulated map for a Gaussian seed, and the local, equilateral and flattened models computed using this seed with the prescription described above. In Fig. [2] we plot the power spectrum for each map, verifying that the non-Gaussian contribution is perturbative for all multipoles.

Needlet bispectrum estimator. We now describe the construction of an estimator for $f_{NL}^B$ using needlets.

To define the family of needlets we will use, consider a smooth weight function $b(t)$ of compact support and satisfying the conditions

1. $b(t) > 0$ only if $t \in [\mu^{-1}, \mu]$ for some $\mu > 1$
2. $\sum_{j=0}^{\infty} b^2(l/\mu^j) = 1$, for $l = 1, 2, \ldots$

We pick a set of ‘scales’ $\mu$ which characterize the needlets used in the analysis, represents as powers of the basic scale $\mu = 1.53$. For each $j$ we choose a set of $n_{\text{pix}}$ points on the sphere, labelled $k$, and denote these points $\xi_{jk}$. Then, the needlet functions $\psi_{jk}(\hat{n})$ are defined by

$$\psi_{jk}(\hat{n}) = \sqrt{\lambda_{jk}} \sum_{l=\mu^{-1}}^{\mu^{j+1}} \sum_{m=-l}^{l} b\left(\frac{l}{\mu^j}\right) Y_{lm}(\hat{n}) Y_{lm}(\xi_{jk}),$$

where the $\lambda_{jk}$ are normalization coefficients which are proportional to the pixel area. Applied to a CMB temperature map $\Delta T(\hat{n})/T$ this yields needlet coefficients

$$\beta_{jk} = \int_{S^2} d^2\hat{n} \frac{\Delta T(\hat{n})}{T} \psi_{jk}(\hat{n}) = \sqrt{\lambda_{jk}} \sum_{l=\mu^{-1}}^{\mu^{j+1}} \sum_{m=-l}^{l} b\left(\frac{l}{\mu^j}\right) a_{lm} Y_{lm}(\xi_{jk})$$

Note that each of the bispectrum simulations is produced for $f_{NL}^B = 1$.

\footnote{The equal area pixel division used by HEALPix (http://healpix.jpl.nasa.gov), the coefficients $\lambda_{jk}$ may be given by an arbitrary constant value.}
Figure 1: Represented clockwise from top left are a purely Gaussian simulation and the bispectrum simulations, computed using equation (9), for the local, equilateral and flattened models, respectively.

Figure 2: The power spectrum corresponding to the simulations of each of the models described in Fig. 1 is plotted. Also plotted are the power spectra computed for three ('diagonal-free') trispectrum models, as shall be described in §IV D and evaluated using equation (41). It is clear that the bispectrum and trispectrum simulations are perturbative compared to the Gaussian part at all multipoles. Plotted from top-to-bottom are the Gaussian model, the flattened, local and equilateral bispectrum models, and the local ($g_{NL}$), constant and equilateral ($c_1$) trispectrum models, respectively.
It has been shown that the mode–mode coupling introduced by masking and anisotropic noise can be accounted for by subtracting, for each scale \( j \), the average over the \( n_{\text{pix}} \) pixels \( k \) \[24\]. Defining the mean for scale \( j \) to be \( \bar{\beta}_j = \frac{1}{n_{\text{pix}}} \sum k \beta_{jk}/n_{\text{pix}} \), this gives \( \beta_{jk} \to \bar{\beta}_{jk} - \bar{\beta}_j \). In what follows we use these subtracted quantities.

In this paper we consider the Mexican needlets defined by the weight function \[19\]. The cubic needlet statistic enables us to define an estimator for the amplitude of the bispectrum \( B \) which is present in the measured CMB bispectrum. Explicitly, we have

\[
\mathbf{b} \left( \frac{l}{\mu} \right) = \left( \frac{l}{\mu} \right)^{2p} \exp \left( -\frac{l^2}{\mu^2} \right),
\]

and choose the coefficients \( \lambda_{jk} \) to be unity. We set \( p = 1 \), for which the Mexican needlets give a good approximation to the Spherical Mexican Hat wavelets at high frequencies, which corresponds here to large \( j \).

The cubic needlet statistic is given by

\[
N_J = \frac{1}{\sigma_{j_1}\sigma_{j_2}\sigma_{j_3}} \sum_{k=0}^{n_{\text{pix}}} \beta_{j_1k}\beta_{j_2k}\beta_{j_3k},
\]

where the triplet index \( J \) represents \((j_1,j_2,j_3)\), and \( \sigma_{j_1} = (4\pi)^{-1} \sum l(l+1)C_l(\mu_1 \mu_2) \). The expectation value of \( N_J \) for a given nonlinear map can be evaluated by computing

\[
\langle N_J^B \rangle = \frac{1}{\sigma_{j_1}\sigma_{j_2}\sigma_{j_3}} \sum_{k=0}^{n_{\text{pix}}} \langle \beta_{j_1k}^G \beta_{j_2k}^G \beta_{j_3k}^B \rangle + 2 \text{ perms},
\]

where the superscripts ‘\( \mathcal{G} \)’ and ‘\( \mathcal{B} \)’ indicate needlet maps computed using, respectively, the Gaussian coefficients \( \beta_{jk}^G \), and non-Gaussian coefficients \( \beta_{jk}^B \) which include the bispectrum \( B \). Using Eqs. \[10\], \[12\] and \[15\] we infer that \( \langle N_J^B \rangle \) can be written

\[
\langle N_J^B \rangle = \sum_n \bar{\alpha}_n^Q \langle N_{nJ}^B \rangle,
\]

where the needlet maps for each mode \( Q_n \), written \( \langle N_{nJ}^B \rangle \), are understood to be defined by this expression. They allow for a change of basis to be performed between needlets and partial waves.

The cubic needlet statistic enables us to define an estimator for the amplitude of the bispectrum \( B \) which is present in the measured CMB bispectrum. Explicitly, we have

\[
\hat{f}_{\mathcal{B}}^\text{NL} = \frac{\sum_J \langle N_J^B \rangle C_{1J}^{-1/2} \hat{N}_J}{\sum_J \langle N_J^B \rangle C_{1J}^{-1}},
\]

where the covariance matrix \( C_{1J} \) is defined by \( C_{1J} \equiv \langle N_J^G N_J^G \rangle - \langle N_J^G \rangle \langle N_J^G \rangle \), and

\[
N_J^G = \frac{1}{\sigma_{j_1}\sigma_{j_2}\sigma_{j_3}} \sum_{k=1}^{n_{\text{pix}}} \beta_{j_1k}^G \beta_{j_2k}^G \beta_{j_3k}^G.
\]

Finally, \( \hat{N}_J \) is the cubic needlet statistic evaluated from the data. We invert the covariance matrix using principal component analysis, imposing a ratio of \( 10^{10} \) between the maximum and minimum eigenvalues which are retained. This approach has been used in other studies of the bispectrum using wavelets \[25\] and needlets \[24\]. The 1-\( \sigma \) error bar on \( \hat{f}_{\mathcal{B}}^\text{NL} \) is

\[
\sigma(\hat{f}_{\mathcal{B}}^\text{NL}) = \left( \sum_J \langle N_J^G \rangle C_{1J}^{-1} \langle N_J^G \rangle \right)^{-1/2}.
\]

Using the change-of-basis matrix \( \langle N_{nJ}^B \rangle \) we may rewrite Eq. \[17\] in the form

\[
\hat{f}_{\mathcal{B}}^\text{NL} = \frac{\sum_n \beta_n^Q \langle N_{nJ}^B \rangle C_{1J}^{-1} \hat{N}_J}{\sum_n \beta_n^Q \langle N_{nJ}^B \rangle C_{1J}^{-1} \langle N_{nJ}^B \rangle} = \frac{\sum_n \beta_n^Q \gamma_{nm} \hat{N}_J}{\sum_n \beta_n^Q \gamma_{nm} \hat{N}_J},
\]

with natural definitions of \( \beta_n^Q \) and \( \gamma_{nm} \), which may be deduced from this equation. Performing the Cholesky decomposition \( \gamma_{nm} = \sum_{\alpha=1}^{n_{\text{pix}}} \lambda_{n\alpha} \lambda_{m\alpha}^\dagger \), and defining \( \beta_n^R = \sum_{\alpha=1}^{n_{\text{pix}}} \lambda_{n\alpha} \beta_n^Q \) and \( \beta_n^G = \sum_{\alpha=1}^{n_{\text{pix}}} \lambda_{m\alpha} \beta_n^Q \), we find that an ensemble of maps simulated with \( \hat{f}_{\mathcal{B}}^\text{NL} = 1 \) satisfy the consistency relation

\[
\langle \beta_n^R \rangle = \hat{f}_{\mathcal{B}}^\text{NL} \\
\langle \beta_n^G \rangle = \hat{f}_{\mathcal{B}}^\text{NL}.
\]

Thus, the coefficients \( \beta_n^Q \) recovered from the needlet maps may be used to reconstruct the underlying bispectrum shape \[8\].
III. CMB TRISPECTRUM WITH NEEDLETS

Primordial trispectrum. The primordial trispectrum $T_\Phi$ is defined by the connected four-point function of the primordial gravitational potential

$$\langle \Phi(k_1)\Phi(k_2)\Phi(k_3)\Phi(k_4) \rangle_c = (2\pi)^3\delta(k_1 + k_2 + k_3 + k_4)T_\Phi(k_1, k_2, k_3, k_4).$$

(22)

In this paper we restrict attention to trispectra which are ‘diagonal’ in the sense that they can be written

$$T_\Phi(k_1, k_2, k_3, k_4) = p(k_1, k_2, k_3, k_4, K_{12}) + p(k_1, k_2, k_3, k_4, K_{13}) + p(k_1, k_2, k_3, k_4, K_{14}),$$

(23)

where $K_{ij} = k_i + k_j$ represents a diagonal of the quadrilateral formed by the momenta $k_i$. The zero-sum condition $\sum_i k_i = 0$ enforced by the momentum-conservation $\delta$-function in (22) means that it is unnecessary to include the remaining combinations $K_{23}$, $K_{24}$ and $K_{34}$. The diagonal condition is not generic: for example, it is not satisfied by the microphysical component of the trispectrum which is generated by interactions near the epoch of horizon exit [26]. However, Eq. (23) often does apply for phenomenological shapes generated with observable amplitude in certain models.

An interesting subclass of diagonal trispectra—including the ‘local’ $g_{\text{NL}}$-shape, the $c_1$ equilateral trispectrum [27] and the constant trispectrum [6]— do not depend on the diagonals $K_{ij}$ but only the individual side-lengths $k_i$. We describe these as ‘diagonal-free’. In particular, the $g_{\text{NL}}$ shape satisfies

$$T_\Phi^{\text{NL}}(k_1, k_2, k_3, k_4) = 6\left(P_\Phi(k_1)P_\Phi(k_2)P_\Phi(k_3) + 3 \text{ perms}\right).$$

(24)

We define the shape function for diagonal-free trispectra by

$$S_T(k_1, k_2, k_3, k_4) = \frac{T_\Phi(k_1, k_2, k_3, k_4)}{T_\Phi^{\text{NL}}(k_1, k_2, k_3, k_4)}.$$  

(25)

Fergusson, Regan & Shellard [6] pointed out that it is possible to decompose these diagonal-free trispectra by analogy with Eq. (1). Labelling unique 4-tuples $(n_1, n_2, n_3, n_4)$ by a multi-index $n$, in the same way that we used a multi-index to label unique triplets in [1], we write

$$S_T(k_1, k_2, k_3, k_4) = \sum_n \alpha_n^{TQ} q_n^{T_q}(k_1)q_n^{T_q}(k_2)q_n^{T_q}(k_3)q_n^{T_q}(k_4).$$

(26)

The basis functions $q_n^{T_q}$ are constructed so that

$$\int_V \left(\prod_{i=1}^4 dx_i\right) q_n^{T_q}(x_1)q_n^{T_q}(x_1) = \delta_{nm},$$

(27)

where the integration domain $V$ is defined by the condition $\sum_i x_i > 2\max\{x_i\}$ and $0 \leq x_i \leq 1$. The expansion coefficients $\alpha_n^{TQ}$ are obtained by defining an inner product analogous to (3) and using this to construct coefficients analogous to (2). For more details on the construction of the $q_n^{T_q}$, the definition of this inner product and the calculation of the expansion coefficients $\alpha_n^{TQ}$ we refer to Refs. [1, 6].

In this paper the only trispectrum we will consider which is not diagonal-free is the local $\tau_{\text{NL}}$-shape given by

$$p^{\tau_{\text{NL}}}(k_1, k_2, k_3, k_4; K) = \frac{25}{9} \left(P_\Phi(k_1) + P_\Phi(k_2)\right)\left(P_\Phi(k_3) + P_\Phi(k_4)\right)P_\Phi(K).$$

(28)

Because this cannot be decomposed using (26), we must deal with this model separately. However, as will be evident from our treatment of the trispectrum in what follows, the formalism discussed in this paper is general and applicable to arbitrary trispectra.

CMB trispectrum: diagonal-free case. The CMB trispectrum is given for diagonal-free trispectra by the connected four-point function of the spherical harmonics of the temperature map

$$\langle a_{l_1 m_1} a_{l_2 m_2} a_{l_3 m_3} a_{l_4 m_4} \rangle_c = \delta_{l_1 l_2 l_3 l_4} \int d^2 \hat{n} Y_{l_1 m_1}(\hat{n})Y_{l_2 m_2}(\hat{n})Y_{l_3 m_3}(\hat{n})Y_{l_4 m_4}(\hat{n}).$$

(29)
where the ‘reduced’ trispectrum $t_{l_1l_2l_3l_4}$ corresponding to the diagonal-free decomposition \cite{20} can be written \cite{11, 16}

$$t_{l_1l_2l_3l_4} = \sum_n \alpha_n^{TQ} \int dx x^2 \bar{q}_{(T,2)}^{(l_1)}(x) \bar{q}_{(T,1)}^{(l_2)}(x) \bar{q}_{(T,1)}^{(l_3)}(x) \bar{q}_{(T,1)}^{(l_4)}(x),$$

(30)

where $\bar{q}_{(T,2)}^{(l_1)}$ and $\bar{q}_{(T,1)}^{(l_2)}$ are defined as in Eq. \cite{5} with $q_n$ replaced by $\bar{q}_n^T$.

We now proceed by analogy with the bispectrum, defining a transfer matrix similar to $\Gamma_{mn}$ which accounts for the line-of-sight integral over the transfer function $\Delta_\alpha$, and expressing the trispectrum in terms of late-time coefficients $\alpha_n^{TQ}$ analogous to those of Eq. \cite{7}. Therefore these results are limited to diagonal-free trispectra. The $\alpha_n^{TQ}$ are chosen to satisfy

$$s^T(l_1, l_2, l_3, l_4) \equiv \frac{t_{l_1l_2l_3l_4}}{C_{l_1}C_{l_2}C_{l_3}C_{l_4}} = \sum_n \alpha_n^{TQ} Q_n^{TQ}(l_1, l_2, l_3, l_4).$$

(31)

We define the inner-product $[f, g]$ by

$$[f, g] = \sum_{l_i} f(l_1, l_2, l_3, l_4) g(l_1, l_2, l_3, l_4) w(l_1, l_2, l_3, l_4),$$

(32)

where the weight function $w$ satisfies

$$w_{l_1l_2l_3l_4} = \frac{1}{32\pi^2} \left[ \int_1^\infty d\mu \prod_{i=1}^4 (2l_i + 1) P_{l_i}(\mu) \right].$$

(33)

This choice is made so that the Fisher matrix is equal to $[s^T, s^T]/24$, which will appear in Eq. \cite{47} below. With all these choices, the late-time coefficients $\alpha_n^{TQ}$ are given by

$$\alpha_n^T = \sum_{rm} \alpha_r^T [\tilde{Q}_r, Q_m]^T H_{rn}^{-1} = \sum_r \alpha_r^T \Gamma_{rn}^T,$$

(34)

where $H_{mn} = [Q^T, Q^T]$ and

$$\tilde{Q}_n(l_1, l_2, l_3, l_4) = (C_{l_1}C_{l_2}C_{l_3}C_{l_4})^{-1/2} \int dx x^2 \bar{q}_{(T,2)}^{(l_1)}(x) \bar{q}_{(T,1)}^{(l_2)}(x) \bar{q}_{(T,1)}^{(l_3)}(x) \bar{q}_{(T,1)}^{(l_4)}(x).$$

(35)

The transfer matrix for the trispectrum is defined by $\Gamma_{mn} = \sum_r [\tilde{Q}_r, Q_m]^T H_{rn}^{-1}$.

**CMB trispectrum: diagonal case.** These results do not apply for trispectra which are not diagonal-free, such as the local $\tau_{NL}$-shape \cite{28}. For a general diagonal trispectrum, the analogue of Eq. \cite{30} is

$$(a_{l_1m_1} a_{l_2m_2} a_{l_3m_3} a_{l_4m_4}) = \sum_{LM} (-1)^M \left[ \frac{1}{4} \int d^2 \hat{n} Y_{l_1m_1}(\hat{n}) Y_{l_2m_2}(\hat{n}) Y_{l_3m_3}(\hat{n}) Y_{l_4m_4}(\hat{n}) \right] \left[ \begin{array}{c} \tilde{G}_{m_1m_2M}^{L1L} G_{m_3m_4M}^{L1L} \end{array} \right] + (2 \leftrightarrow 3) + (2 \leftrightarrow 4),$$

(36)

where $G_{m_1m_2M}^{L1L} \equiv \int d^2 \hat{n} Y_{l_1m_1}(\hat{n}) Y_{l_2m_2}(\hat{n}) Y_{l_3m_3}(\hat{n}) Y_{l_4m_4}(\hat{n})$ and $(2 \leftrightarrow 3), (2 \leftrightarrow 4)$ represent the previous expression with the labels 2, 3 and 2, 4 exchanged, respectively. For example, the local $\tau_{NL}$-shape given in Eq. \cite{28} results in the CMB trispectrum

$$\tilde{p}_{l_1l_2l_3}^{l_4}(L) = \int dr_1 dr_2 r_1^2 r_2^2 F_L(r_1, r_2) \left[ \alpha_1(r_1) \beta_{l_1}(r_1) + \alpha_2(r_1) \beta_{l_1}(r_1) \right] \left[ \alpha_3(r_3) \beta_{l_1}(r_2) + \alpha_4(r_3) \beta_{l_1}(r_2) \right],$$

(37)

where

$$F_L(r_1, r_2) = \int dK K^2 P_b(K) j_L(Kr_1) j_L(Kr_2),$$

(38a)

$$\alpha_1(x) = \int dk k^2 \Delta_{l_1}(k) j_l(kx),$$

(38b)

$$\beta_1(x) = \int dk k^2 P_b(k) \Delta_{l_1}(k) j_l(kx).$$

(38c)
Note that, despite the similarity of notation, \( \alpha_i, \beta_i \) as defined here are distinct from the decomposition coefficients \( \alpha_n^Q, \alpha_n^{TQ} \) and the needlet coefficients \( \beta_{jk}, \beta_j \). The definitions (38b)-(38c) are conventional.

It was shown by Pearson et al. that the following approximation is accurate to within \( \lesssim 2\% \) [28],

\[
p_{l_1l_2l_4}^{TQ} \approx C_L^{TQ}(C_{l_1} + C_{l_2})(C_{l_3} + C_{l_4}),
\]

(39)

where \( C_L^{TQ} = (25/9) \int dK K^2 P_B(K) j_{l_1}(Kr_s)^2 \) is the angular power spectrum of the curvature perturbation \( \zeta \), and \( r_s \) represents the distance to the last scattering surface.

**Simulating the CMB trispectrum.** As in [11] we fix a choice of trispectrum \( T(k_1,k_2,k_3,k_4) \) and include it in the trispectrum of the primordial gravitational potential with amplitude \( g_{NL} \), so that \( T_p(k_1,k_2,k_3,k_4) \supset g_{NL}^2 T(k_1,k_2,k_3,k_4) \). As for \( f^2_{NL} \), it is important to be clear that \( g_{NL}^2 \) does not coincide with the traditional local \( g_{NL} \)-parameter [29] unless \( T \) is the conventionally-normalized local trispectrum [24]. In this paper, the traditional local \( g_{NL} \)-parameter is always denoted \( g_{NL}^{loc} \). Our task is to build an estimator for \( g_{NL} \).

To estimate the covariance matrix we must again construct averages over an ensemble of maps which contain the trispectrum \( T \). For the analysis in this section, and for the constraints reported in [IV] below, we will assume that there is no primordial bispectrum. It follows that we may utilise the late-time CMB trispectrum expansion given by equation (31), and write

\[
a_{lm}^T = 1 \frac{1}{8} \sum_{LM} \sum_{l_i m_i} (-1)^M P_{l_1l_2l_4}(L) g_{m_2l_2}^{Q} (\hat{g}^{Q})^{LM} \frac{a_{l_2m_2}^{G+} a_{l_4m_4}^{G+} a_{l_2m_4}^{G+} a_{l_4m_2}^{G+}}{C_{l_2} C_{l_4}}.
\]

(40)

In the case of diagonal-free trispectra we may instead use the expression [4, 6]

\[
a_{lm}^T = 1 \frac{1}{24} \sum_{l_i m_i} t_{l_1l_2l_4} \int d^2 \hat{n} Y_{lm}(\hat{n}) Y_{l_1m_1}(\hat{n}) Y_{l_2m_2}(\hat{n}) Y_{l_4m_4}(\hat{n}) \frac{a_{l_2m_2}^{G+} a_{l_4m_4}^{G+} a_{l_2m_4}^{G+} a_{l_4m_2}^{G+}}{C_{l_2} C_{l_4}},
\]

(41)

where \( \hat{M}^{-(1)}(T,G)(x,\hat{n}) = \sum_{lm} \tilde{q}^{(-1),T} q_{lm} M_{lm}(\hat{n})/C_l \). Alternatively, using a similar approach to that described for the bispectrum, we may utilise the late-time CMB trispectrum expansion given by equation (31), and write

\[
a_{lm}^T = \sum_{n} a_n^{TQ} \sqrt{C_l} \int d^2 \hat{n} Y_{lm}(\hat{n}) q_{ln}(\frac{l}{l_{\text{max}}}) M_{l2n}(\hat{n}) M_{l3n}(\hat{n}) M_{l4n}(\hat{n}),
\]

(42)

where \( M_{l2n}(\hat{n}) = \sum_{lm} q_{lm}\int_{l_{\text{max}}}^{l_{\text{max}}} a_{l2m} M_{lm}(\hat{n})/\sqrt{C_l} \). Using equation (41), in Fig. [2] we plot the simulated maps for the local \( (g_{NL}) \), equilateral \( (e_1) \) and constant trispectrum models, which will be described in [IV D]. The corresponding power spectra are plotted in Fig. [2] emphasising the perturbative nature of the trispectra compared to the Gaussian seed.

However we choose to obtain the \( a_{lm}^T \), we define the quartic needlet statistic by

\[
N_{ij}^T = 1 \frac{1}{\sigma_j \sigma_j \sigma_j \sigma_j} \sum_{k=1}^{n_{\text{pix}}} \beta_{j_1k} \beta_{j_2k} \beta_{j_3k} \beta_{j_4k} \beta_{j_4k} + 3 \text{ perms},
\]

(43)
where $J$ represents the unique 4-tuple $(j_1, j_2, j_3, j_4)$ and the $\beta_{jk}$ are the needlet coefficients defined in Eq. (12). A superscript ‘G’ indicates that these coefficients are to be computed using a Gaussian map, and the superscript ‘T’ indicates that they should be computed from a map which includes the trispectrum correction $a_{lm}^t$. We use Eq. (12) to write the expectation value of $N_J^T$ over an ensemble of maps

$$\langle N_J^T \rangle = \sum_n \alpha_n^{TQ} \langle N_{nlJ}^T \rangle,$$

(44)

As above, the change-of-basis matrix $\langle N_{nlJ}^T \rangle$ is defined by this expression.

In the case of the $\tau_{nl}$ trispectrum we may utilize equations (39) and (40) in order to write

$$\langle N_{J\tau_{nl}}^T \rangle = \sum_L C_L^\tau \langle N_{IJL}^{T\tau_{nl}} \rangle \equiv \sum_L C_L^\tau \sum_M 4 \int d^2 n \ Y_{LM}(\hat{\mathbf{n}}) \tilde{\beta}_{ij}(\hat{\mathbf{n}}) \tilde{\beta}_{ij}(\hat{\mathbf{n}}) \int d^2 \hat{\mathbf{n}} \ Y_{LM}^*(\hat{\mathbf{n}}) \tilde{\beta}_{ij}(\hat{\mathbf{n}}) \tilde{\beta}_{ij}(\hat{\mathbf{n}}),$$

(45)

where we express $\tilde{\beta}_{ij}$ as $\tilde{\beta}_{ij}(\hat{\mathbf{n}})$, with tilde representing a needlet map, (12), with appropriate weighting determined by equation (39). The beam and mask properties must also be accounted for via a transformation of these spherical harmonics, as will be described in IV

**Needlet trispectrum estimator.** In Ref. [4], the Edgeworth expansion was used to derive the optimal trispectrum estimator. This was

$$\mathcal{E}_{opt} = \sum_{l,m_1,m_2} \langle \prod_{i=1}^4 a_{li,m_i} \rangle \ C_{l_1 m_1 \ell_1 m_1}^{-1} C_{l_2 m_2 \ell_2 m_2}^{-1} C_{l_3 m_3 \ell_3 m_3}^{-1} C_{l_4 m_4 \ell_4 m_4}^{-1} \times \left[ \langle \prod_{i=1}^4 a_{l_i m_i} \rangle - \langle C_{l_1 m_1 \ell_1 m_1} a_{l_2 m_2} a_{l_3 m_3} a_{l_4 m_4} + 5 \text{ perms} \rangle + \langle C_{l_1 m_1 \ell_1 m_1} a_{l_2 m_2} a_{l_3 m_3} a_{l_4 m_4} + 2 \text{ perms} \rangle \right],$$

(46)

where $C_{l_1 m_1 \ell_1 m_1} = \langle a_{l_1 m_1} a_{l_2 m_2} \rangle$. Approximating the inverse covariance matrix as diagonal, i.e. $C_{l_1 m_1 \ell_1 m_1}^{-1} = \delta_{l_1, \ell_1} \delta_{m_1, -m_1} / C_{l_1}^{-1}$, it follows that the Fisher matrix $F \equiv \langle \mathcal{E}_{opt} \rangle / 24$ roughly satisfies

$$F \approx \frac{f_{sky}}{24} \sum_{l,m_1,\ell,m_2} C_{l_1} C_{l_2} C_{l_1} C_{l_3} \langle \prod_{i=1}^4 a_{l_i m_i} \rangle^2,$$

(47)

where $f_{sky}$ represents the sky fraction covered by the map and $C_{l_1}$ is the total power spectrum, including beam effects and noise contributions. It was this approximate expression that was used in Refs. [4, 6]. A similar estimator may be derived for needlets, with the inverse covariance matrix used to optimize the signal to noise. The estimator may be used to give an estimate for the trispectrum amplitude, $\hat{\gamma}_{nl}^T \equiv \mathcal{E} / \langle \mathcal{E} \rangle$. We find

$$\hat{\gamma}_{nl}^T \equiv \frac{\sum_{IJ} \langle N_J^T \rangle \ C_{IJ}^{-1} \hat{N}_J}{\sum_{IJ} \langle N_J^T \rangle \ C_{IJ}^{-1} \langle N_J \rangle},$$

(48)

where $\hat{N}_J$ is to be obtained from the data,

$$\hat{N}_J = \bar{N}_J - \left( \frac{\sum_k \langle \partial G^G_{jk} \partial G^G_{jk} \rangle_{\ell_1 m_1 \ell_2 m_2}}{n_{pix} \prod_i \sigma_i j_i} + 5 \text{ perms} \right) + \sum_k \langle \partial G^G_{jk} \partial G^G_{jk} \partial G^G_{jk} \rangle_{\ell_1 m_1 \ell_1 m_1} / n_{pix} \prod_i \sigma_i j_i,$$

(49)

with the covariance matrix defined by $C_{IJ} = \langle N_J^T N_J^T \rangle - \langle N_J^T \rangle \langle N_J \rangle$. The 1-sigma error bar is $\Delta \hat{\gamma}_{nl}^T \equiv \langle \mathcal{E} \rangle^{-1/2}$. For the special case of diagonal-free trispectra, where the decomposition (31) applies, we may write the trispectrum needlet map in the form (44). Then the needlet estimator becomes

$$\hat{\gamma}_{nl}^T \equiv \sum_{nm} \alpha_n^{TQ} \langle N_{nlm}^T \rangle C_{IJ}^{-1} \hat{N}_J = \sum_{nm} \alpha_n^{TQ} \beta_n^{TQ} C_{IJ}^{-1} \langle N_{nlm}^T \rangle,$$

(50)

where $\gamma_{nm}^T = \sum_{IJ} \langle N_{nlm}^T \rangle C_{IJ}^{-1} \langle N_{nlm}^T \rangle$ represents the covariance matrix projected into modal space and is notationally the same as the matrix $\gamma_{nm}$ defined in Eq. (20), except that it should be computed using maps including the trispectrum contribution $T$ rather than a bispectrum contribution from $B$. In equation (50) we have defined $\beta_n^{TQ} \equiv \langle N_{nlm}^T \rangle C_{IJ}^{-1} \hat{N}_J.$
In the case of the local $\tau_{\text{NL}}$ trispectrum, using equation (43), the estimator may be written in the form

$$\hat{\tau}_{\text{NL}} = \frac{\sum_i C_L^{a_i} \sum_j (N_{L i}^{T,\text{NL}}) C_j^{-1} N_j}{\sum_i C_L^{a_i} \sum_j (N_{L i}^{T,\text{NL}}) C_j^{-1} (N_{L i}^{T,\text{NL}}) C_j^{-1}} = \frac{\sum_i C_L^{a_i} D_L}{\sum_i C_L^{a_i} G_{LL'} C_L^{-1}},$$  

(51)

with the 1σ error bar given by $1/\sqrt{3 \sum_i C_L^{a_i} G_{LL'} C_L^{-1}}$, and where the quantities $D_L$ and $G_{LL'}$ may be inferred from the second and third equalities. The factor of 3 arises due to the three instances of $l_{\text{side}}^2$ in the CMB trispectrum (36). In the application of this estimator we restrict the range of $L$ to $1 \leq L \leq L_{\text{max}} = 50$.

IV. APPLICATION TO 9-YEAR WMAP DATA

In this section we apply the formalism described in §§[1][11] to the foreground-cleaned, coadded $V + W$ maps from the 9-year WMAP data release [30]. We work up to $l_{\text{max}} = 1000$. The data are supplied in HEALPix format with a resolution of 6.9 arcmin and $N_{\text{side}} = 512$, together with the necessary beam and noise properties to perform realistic simulations. In this analysis we use cosmological parameters corresponding to those of the WMAP9 fiducial cosmology, given in Table[1]

<table>
<thead>
<tr>
<th>$\Omega_b h^2$</th>
<th>$\Omega_c h^2$</th>
<th>$\Omega_\Lambda$</th>
<th>$\tau$</th>
<th>$A_\Phi$</th>
<th>$n_s$</th>
</tr>
</thead>
<tbody>
<tr>
<td>0.02256</td>
<td>0.11142</td>
<td>0.7185</td>
<td>0.0851</td>
<td>1.705 $\times 10^{-8}$</td>
<td>0.971</td>
</tr>
</tbody>
</table>

Table 1: Parameters for the WMAP9 fiducial cosmology [30]. The optical depth is measured by $\tau$. The parameters $A_\Phi$ and $n_s$ parametrize the primordial power spectrum, with $P_\Phi(k) = A_\Phi(k/k_p)^{-n_s}$, the pivot scale $k_p$ is chosen to be $k_p = 0.0026$ Mpc$^{-1}$.

Simulated maps. We simulate the Gaussian spherical harmonics amplitudes $a_{lm}^G$, with a variance given by the angular power spectrum $C_\ell$. The non-Gaussian amplitudes $a_{lm}^B$ and $a_{lm}^T$ are simulated according to the prescriptions outlined in §§[1][11] in particular Eqs. (10) and (40)–(41). We incorporate the effect of the WMAP beam $b_i$ and noise $n_{im}$ for each channel $X \in \{V_1, V_2, W_1, W_2, W_3, W_4\}$ by making that transformation

$$a_{im} \rightarrow \tilde{a}_{im} = b_i a_{im} + n_{im}.$$  

(52)

For each data channel, $i$, we model $n_{im}$ as white noise with variance per pixel given by $N_i(\tilde{n}) \equiv \sigma_{0,i}/\sqrt{N_{i,\text{obs}}}$ where $\sigma_{0,i}$ is the sensitivity per data channel, and $N_{i,\text{obs}}(\tilde{n})$ represents the corresponding number of observations per pixel. The simulations and data maps for each channel, $M_i(\tilde{n})$, are coadded optimally with inverse noise weighting per pixel, i.e.

$$M(\tilde{n}) = \frac{\sum_{i \in X} M_i(\tilde{n}) N_i(\tilde{n})^{-2}}{\sum_{i \in X} N_i(\tilde{n})^{-2}},$$  

(53)

where $X$ is the set of channels defined above [25].

We apply a suitable mask and remove the monopole and dipole using HEALPix. The map is then re-decomposed into spherical harmonics, and needlet maps are evaluated by convolving with the needlet function $\psi_{jk}$ as in [12]. For the bispectrum we choose weight functions by setting $\mu = 1.53$ and $j = 3, 4, 5, \ldots, 15, 16$ giving fifteen distinct scales. Therefore there are $\left(\frac{15+2}{2}\right) = 680$ distinct cubic statistics $N_j$. For the trispectrum it is not necessary to use all scales because they provide little extra information, so we thin the range and choose $j = 0, 4, 6, 8, 9, \ldots, 15$. We will show later that this thinning does not impair the optimality of the estimator. These choices give 11 distinct scales, and therefore $\left(\frac{11+3}{4}\right) = 1001$ distinct quartic statistics.

As described in §§[1] we subtract the mean from each wavelet coefficient, setting $\beta_{jk} \rightarrow \beta_{jk} - \bar{\beta}_j$, and evaluate the covariance matrix $C_{ij}$ for the bi- and trispectrum estimators. This requires computation of the ensemble averages $\langle N_j N_j \rangle$ and $\langle N_j^T N_j^T \rangle$, together with the corresponding one-point statistics $\langle N_j \rangle$ and $\langle N_j^T \rangle$. For the bispectrum estimator we use a suite of 60,000 simulations. For the trispectrum estimator we use a suite of 300,000 simulations because we find that more samples are required to achieve convergence. The $\tau_{\text{NL}}$ model requires special treatment, and it is necessary to compute its associated one-point statistic $\langle N_I N_I^T \rangle$, using (45). In each case we evaluate the inverse covariance matrix $C_{ij}^{-1}$ using principal component analysis, keeping only eigenvalues up to a factor $10^{11}$ smaller than
We evaluate the change-of-basis matrices $\langle N_n I \rangle$ and $\langle N^T_n I \rangle$ using 1,000 simulations. Finally, the trispectrum estimators (48) and (51) require the two-point expectation value $\langle \beta_G G^j \beta_G^k \rangle$, which we obtain using 50,000 Gaussian simulations.

At the end of this process we are able to estimate the observables $f_{NL}$, $g_{NL}$, and $\tau_{NL}$. For $\tau_{NL}$ we may immediately apply Eq. (51), whereas $f_{NL}$ and $g_{NL}$ first require a suitable decomposition of the primordial bi- and tri-spectra $B$ and $T$. As explained in §§II–III, for the bi- and tri-spectrum we fold the transfer function $\Delta l$ and the line-of-sight integral into the respective transfer matrices $\Gamma_{nm}$ and $\Gamma^T_{nm}$ for computation of a decomposition of the CMB shapes.

### A. Validation procedure

To verify that both the cubic and quartic estimators are unbiased we apply them to 2,000 Gaussian simulations. The mean of each recovered cubic and quartic coefficient, $\bar{\beta}_R^n$ and $\bar{\beta}_{RT}^n$, respectively, are verified to be consistent with zero within two standard errors of the mean. For the local bispectrum mode and local $g_{NL}$-mode trispectrum we find

$$\langle \hat{f}_{\text{loc}}^{NL} \rangle = 0.1 \pm 23.1,$$

$$\langle \hat{g}_{\text{loc}}^{NL} \rangle = [0.03 \pm 2.33] \times 10^5.$$ (54a) (54b)

The error bar for $\langle \hat{g}_{\text{loc}}^{NL} \rangle$ establishes that the procedure described in this paper is close to optimal, because in Ref. [21] the optimal error bar was shown to be $2.2 \times 10^5$.

This establishes that the estimator correctly gives zero when applied to Gaussian maps, but it is also necessary to check that it recovers the correct non-Gaussian amplitude when applied to non-Gaussian maps. We test this using 200 simulations of the local-mode bispectrum and $f_{NL}^{loc} = 100$, constructed using the method described by Hanson et al. [31]. We recover the result $\langle f_{NL}^{loc} \rangle = 100.3 \pm 0.34$, where the error bar represents the standard error of the mean.

In Fig. 4 we plot the eigenvalues for both the bispectrum (cubic statistics) and trispectrum (quartic statistics), in order to assess the number of elements included in the analysis after applying principal-component analysis to the covariance matrix. The indicated cutoff value is $10^{-11}$ times the maximum eigenvalue.

### B. Point source Simulations

To estimate the effect of unresolved point sources we adopt the constant-flux model described in Ref. [32]. We assume that a population of sources, each with constant flux $F_{\text{src}}$, and number density $n_{\text{src}}$ per steradian, contaminate each

4 We have verified that our results are independent of the precise cut which is chosen.
pixel with a frequency-dependent temperature increment \( \delta T_{\text{arc}}(\hat{n}) = F_{\text{arc}}g(x)(\hat{n})/\Omega_{\text{pix}} \), where \( \Omega_{\text{pix}} = 1/n_{\text{pix}} \) is the solid angle per pixel and \( x = h\nu/k_{\text{B}}T_{\text{CMB}} = \nu/(56.8 \, \text{GHz}) \). The function \( g(x) \) satisfies

\[
g(x) = \frac{\sinh^2(x/2)}{x^4} \frac{1}{24.8 \, \text{Jy K}^{-1} \text{sr}^{-1}}
\]

and represents the conversion factor between brightness and temperature \( ^{33} \). Finally, \( \epsilon(\hat{n}) \) is a Poisson-distributed random variable with mean \( n_{\text{arc}}\Omega_{\text{pix}} \). This Poisson distribution of sources introduces a non-Gaussian signature. This constant-flux model satisfactorily reproduces the power spectrum and bispectrum of point sources measured by the WMAP team \( ^{32,34} \), given the values \( F_{\text{arc}} = 0.5 \, \text{Jy} \) and a source density of \( n_{\text{arc}} = 85 \, \text{sr}^{-1} \).

To estimate the influence of point sources on the estimators described above, we perform a separate set of 1,000 simulations in which we construct a set of Gaussian maps using \( ^{52,53} \) and \( ^{54} \). These maps are modified by adding a point-source contamination according to the prescription above. We compute the cubic and quartic needlet statistics both with and without point sources. Taking the difference for each realization gives an estimate of the bias on \( f_{NL}^B \) or \( g_{NL}^T \) for each primordial shape of interest. We give numerical results in Table II.

C. Bispectrum Constraints

In this section we tabulate the constraints and estimated point source contamination for the local, DBI, equilateral, constant, orthogonal and flattened bispectrum models. Constraints for these models have previously been published by Fergusson, Liguori & Shellard based on the KSW estimator \( ^{35} \) and using a wavelet-based estimator in Ref. \( ^{36} \).

- **Local model.** A Taylor expansion around a Gaussian gravitational potential \( \phi_G \) defines both the local-mode bispectrum and local \( g_{NL}^T \)-mode trispectrum. It accurately represents the type of non-Gaussianity generated by evolution on superhorizon scales in multiple-field inflationary models \( ^{20,35} \) or the curvaton model \( ^{36,38} \). We write \( ^{39} \)

\[
\Phi(x) = \Phi_G(x) + f_{NL}^{\text{loc}}(\Phi_G(x)^2 - (\Phi_G(x))^2) + g_{NL}^{\text{loc}}\Phi_G(x)^3 + \ldots .
\]

The resulting primordial bispectrum is given by

\[
B_{\Phi}(k_1, k_2, k_3) = 2f_{NL}^{\text{loc}}(P_{\Phi}(k_1)P_{\Phi}(k_2) + P_{\Phi}(k_1)P_{\Phi}(k_3) + P_{\Phi}(k_2)P_{\Phi}(k_3)).
\]

Our constraints on \( f_{NL}^{\text{loc}} \) and the bias \( \Delta f_{NL}^{\text{loc}} \) due to point sources are

\[
f_{NL}^{\text{loc}} = 38.6 \pm 23.1 \quad \text{and} \quad \Delta f_{NL}^{\text{loc}} = 9.6 \pm 4.1.
\]

This result is consistent with the needlet-based constraint \( f_{NL}^{\text{loc}} = 37.5 \pm 21.8 \) reported by Donzelli et al. \( ^{24} \), and with the wavelet-based constraint \( f_{NL}^{\text{loc}} = 38.4 \pm 23.6 \) reported in Ref. \( ^{36} \).

The lower error bar in the case of Donzelli et al. \( ^{24} \) may be partly attributed to the larger number of needlet scales used in that work, as well as the use of a linear term correction. We have chosen to ignore the linear correction term in this work, because Refs. \( ^{36,38} \) demonstrated (in the case of wavelets) that it leads to only a \( \lesssim 2\% \) correction; the mean scale subtraction largely accounting for anisotropies due to the mask and noise. In addition the remaining bispectrum models achieve optimality and therefore we persist with only 15 needlet scales. However, we note that to achieve optimality in the case of the local model, we may require more scales. While this issue is somewhat parenthetic to the aims of this paper, we present an investigation of the dependency of the results on the maximum and minimum needlet scale in Fig. 5.

The estimate for the bias due to point sources given in \( ^{38} \) for the contribution of point sources is larger than predicted using wavelets, which give \( \Delta f_{NL}^{\text{loc}} = 3.1 \pm 3.7 \) \( ^{36} \).

- **DBI and equilateral models.** Under certain circumstances, non-standard kinetic terms may lead to strong self-interactions between modes as they leave the horizon \( ^{40,42} \). An example is DBI inflation, for which the equilateral model provides an accurate separable approximation. The bispectra are

\[
B_{\Phi}^{\text{DBI}} = \frac{1}{(k_1k_2k_3)^3(\sum_i k_i)^2} \left( \sum_i k_i^4 + \sum_{i \neq j} (2k_i^2k_j - 3k_i^3k_j^2) + \sum_{i \neq j \neq l} (k_i^3k_jk_l - 4k_i^2k_j^2k_l) \right),
\]

\[
B_{\Phi}^{\text{eq}} = 6 \left( - \left[ P_{\Phi}(k_1)P_{\Phi}(k_2) + 2 \text{ perms} \right] - 2 \left[ P_{\Phi}(k_1)P_{\Phi}(k_2)P_{\Phi}(k_3) \right]^{2/3} + \left[ P_{\Phi}^{1/3}(k_1)P_{\Phi}^{2/3}(k_2)P_{\Phi}(k_3) + 5 \text{ perms} \right] \right).
\]
The needle-based estimator gives
\[
\text{f}^\text{DBI}_{\text{NL}} = 65.5 \pm 99.4, \quad \text{f}^\text{NL}_{\text{const}} = 64.5 \pm 117.3, \quad \Delta \text{f}^\text{DBI}_{\text{NL}} = 9.5 \pm 14.1, \quad \Delta \text{f}^\text{NL}_{\text{const}} = 11.0 \pm 19.3. \quad (61)
\]

- **Constant model.** The constant model gives a primordial bispectrum corresponding to
\[
B^\text{const}_\Phi(k_1, k_2, k_3) = 6(P_\Phi(k_1)P_\Phi(k_2)P_\Phi(k_3))^{2/3}.
\]

The CMB bispectrum is entirely due to the transfer function; see Ref. \[43\] for a possible microphysical realization. The needle estimator gives
\[
f^\text{const}_{\text{NL}} = 60.8 \pm 62.7, \quad \Delta f^\text{const}_{\text{NL}} = 9.3 \pm 9.9. \quad (63)
\]

- **Orthogonal model.** The orthogonal model is given by a linear combination of the equilateral and constant models, \(B^\text{orthog}_\Phi = 3B^\text{eq}_\Phi - 2B^\text{const}_\Phi\). We obtain
\[
f^\text{orthog}_{\text{NL}} = -175.0 \pm 101.8, \quad \Delta f^\text{orthog}_{\text{NL}} = -24.3 \pm 16.7. \quad (64)
\]

For comparison, the constraint from 7-year WMAP data using the wavelet-based estimator of Ref. \[8\] was \(f^\text{orthog}_{\text{NL}} = -173.2 \pm 101.4\). By comparison, the WMAP team report \(f^\text{orthog}_{\text{NL}} = -245 \pm 100\) from the 9-year data \[30\]. The constraint given in \[64\] uses 9-year data and is consistent with the 7-year result. It is substantially less significant than the result obtained by the WMAP team. Below, we investigate this further by providing a frequency-band analysis.

- **Flattened model.** A ‘flattened’ configuration may be produced by a nontrivial initial state, including a non-Bunch–Davies vacuum. For such states, long-lived excitations with nearly zero energy can be formed by a combination of positive- and negative-energy modes. These generate strong correlations. Physical models realizing this effect are discussed, for example, in Refs. \[44\], \[45\]. The bispectrum is
\[
B^\text{flat}_\Phi = \frac{6}{39(k_1k_2k_3)^2} \left[ \left( \frac{k_1^4 + k_2^4 - k_3^4}{k_2k_3} + 2 \text{ perms} \right) + 12 + 8 \left( \frac{k_1k_2 + k_1k_3 - k_2k_3}{(k_2 + k_3 - k_1)^2} + 2 \text{ perms} \right) \right]. \quad (65)
\]

In order to handle the divergence we set the bispectrum to zero for \(k_1 + k_2 - k_3 < Z \sum_i k_i\) (or its permutations) with \(Z = 0.03\) and employ a low pass (Gaussian) filter in order to smoothen the shape near the edges as in Ref. \[3\]. The resulting constraints are
\[
f^\text{flat}_{\text{NL}} = 14.9 \pm 10.5, \quad \Delta f^\text{flat}_{\text{NL}} = 2.5 \pm 1.7. \quad (66)
\]

<table>
<thead>
<tr>
<th>Shape</th>
<th>V-band</th>
<th>W-band</th>
<th>V+W</th>
<th>V-band</th>
<th>W-band</th>
<th>V+W</th>
</tr>
</thead>
<tbody>
<tr>
<td>Local</td>
<td>44.0 ± 26.2</td>
<td>30.2 ± 26.6</td>
<td>38.6 ± 23.1</td>
<td>12.0 ± 5.1</td>
<td>1.6 ± 2.4</td>
<td>9.6 ± 4.1</td>
</tr>
<tr>
<td>DBI</td>
<td>53.3 ± 106.4</td>
<td>86.4 ± 107.2</td>
<td>65.5 ± 99.4</td>
<td>31.9 ± 18.5</td>
<td>3.5 ± 9.1</td>
<td>9.5 ± 16.1</td>
</tr>
<tr>
<td>Equilateral</td>
<td>54.2 ± 125.6</td>
<td>88.6 ± 126.7</td>
<td>64.5 ± 117.3</td>
<td>38.3 ± 22.2</td>
<td>4.4 ± 10.9</td>
<td>11.0 ± 19.3</td>
</tr>
<tr>
<td>Constant</td>
<td>54.1 ± 67.5</td>
<td>85.1 ± 67.6</td>
<td>60.8 ± 62.7</td>
<td>22.8 ± 11.6</td>
<td>2.6 ± 5.7</td>
<td>9.3 ± 9.9</td>
</tr>
<tr>
<td>Orthogonal</td>
<td>−154.7 ± 114.9</td>
<td>−182.8 ± 114.0</td>
<td>−175.0 ± 101.8</td>
<td>−36.0 ± 20.1</td>
<td>−3.9 ± 9.6</td>
<td>−24.3 ± 16.7</td>
</tr>
<tr>
<td>Flat</td>
<td>13.1 ± 11.6</td>
<td>15.6 ± 11.6</td>
<td>14.9 ± 10.5</td>
<td>4.7 ± 2.1</td>
<td>0.6 ± 1.0</td>
<td>2.5 ± 1.7</td>
</tr>
</tbody>
</table>

**Table II:** Constraints on the various bispectrum shapes computed for, respectively, the V-band, W-band and coadded data. The last three columns give estimates for the point source contamination in each case.
**Frequency dependence.** Instead of using the entire dataset, it is possible to obtain constraints using only V- or W-band data and corresponding simulations of the maps and covariance matrix. The bias due to point sources can be taken into account as described above. We tabulate our results in Tables II and III.

We find that point-source contamination in the V-band is more significant than in the W-band. In comparison to alternative estimators, such as Spherical Mexican Hat wavelets, needlets show more sensitivity to point-source contamination of the local shape. The frequency-band analysis shows that the V- and W-band constraints are consistent for each model (within 1-σ), including for the orthogonal shape for which the WMAP team obtained disrepan results from the 9-year data \( f_{\text{orthog}} = -245.5 \pm 99.6 \) from the coadded map, \( f_{\text{orthog}} = -125.9 \pm 112.7 \) from V-band only, and \( f_{\text{orthog}} = -320.2 \pm 112.1 \) from W-band only). The needlet-based analysis given here produces much weaker frequency dependence.

<table>
<thead>
<tr>
<th>Shape</th>
<th>V-band</th>
<th>W-band</th>
<th>V+W</th>
</tr>
</thead>
<tbody>
<tr>
<td>Local</td>
<td>32.0 ± 26.2</td>
<td>28.6 ± 26.6</td>
<td>29.0 ± 23.1</td>
</tr>
<tr>
<td>DBI</td>
<td>21.4 ± 106.4</td>
<td>82.9 ± 107.2</td>
<td>56.0 ± 99.4</td>
</tr>
<tr>
<td>Equilateral</td>
<td>15.9 ± 125.6</td>
<td>84.2 ± 126.7</td>
<td>53.5 ± 117.3</td>
</tr>
<tr>
<td>Constant</td>
<td>31.3 ± 67.5</td>
<td>82.5 ± 67.6</td>
<td>51.5 ± 62.7</td>
</tr>
<tr>
<td>Orthogonal</td>
<td>−118.7 ± 114.9</td>
<td>−178.9 ± 114.0</td>
<td>−150.7 ± 101.8</td>
</tr>
<tr>
<td>Flat</td>
<td>8.4 ± 11.6</td>
<td>15.0 ± 11.6</td>
<td>12.4 ± 10.5</td>
</tr>
</tbody>
</table>

**Table III:** Constraints on bispectrum models corrected for the effect of point sources (see Table II).

**Point Source Model Investigation.** One may be concerned that the constant-flux point source model described in §4 is too simplistic. Therefore, we also implement a more realistic point source model which provides a better match to observations at each flux value. We use the analytic fit \( 23 \) to the de Zotti et al. \( 17 \) observations, with the proper distribution of number counts \( dn/dS = AS^{-\alpha} \), where \( A = 22.1 \pm 1.5 \) and \( \alpha = 2.32 \pm 0.06 \) with the best fit value chosen for our simulations. Extending the constant-flux model we integrate over fluxes using this model with \( S \in [10^{-3}, 1] \) Jy. In Table IV we list the corresponding estimates for the contamination due to point sources. Comparison to Table II reveals the consistency of the results obtained using both point source models. In the context of searches for primordial non-Gaussianity beyond Planck, more detailed source modelling may be necessary. Indeed, the extra intensity of the point source contamination in the V-band suggests the impact of radio-sources. A study of different families of point sources was performed in Ref. \( 18 \) detailing the potentially strong non-Gaussian deviations due to unresolved point sources for both high (> 225GHz) and low (< 100GHz) frequency data.

<table>
<thead>
<tr>
<th>Shape</th>
<th>V-band</th>
<th>W-band</th>
<th>V+W</th>
</tr>
</thead>
<tbody>
<tr>
<td>Local</td>
<td>15.3 ± 5.3</td>
<td>2.2 ± 7.1</td>
<td>10.8 ± 4.8</td>
</tr>
<tr>
<td>DBI</td>
<td>37.4 ± 23.7</td>
<td>6.6 ± 13.7</td>
<td>7.5 ± 11.1</td>
</tr>
<tr>
<td>Equilateral</td>
<td>44.4 ± 27.2</td>
<td>8.0 ± 15.6</td>
<td>7.9 ± 17.0</td>
</tr>
<tr>
<td>Constant</td>
<td>27.4 ± 13.2</td>
<td>4.6 ± 10.1</td>
<td>8.9 ± 8.9</td>
</tr>
<tr>
<td>Orthogonal</td>
<td>−47.3 ± 23.3</td>
<td>−6.8 ± 22.6</td>
<td>−29.2 ± 18.6</td>
</tr>
<tr>
<td>Flat</td>
<td>5.8 ± 1.9</td>
<td>0.9 ± 2.1</td>
<td>2.7 ± 1.6</td>
</tr>
</tbody>
</table>

**Table IV:** Estimates for the point source contamination for each bispectrum model considered, for the V-, W- and coadded data, using the more realistic point source model. Comparison to Table II reveals the consistency with the results obtained using the more simplistic constant flux model.

\(^5\) We thank an anonymous referee for drawing our attention to this detail.
Figure 5: Plotted on the left column is the dependency of the best fit value - and error bar - of $f_{NL}$ on the maximum needlet scale. The triangle glyph represents the best fit value, while shading is used to represent the region $f_{NL} \in [-\Delta f_{NL}, \Delta f_{NL}]$. Represented are the constraints using all measured needlet data up to the maximum scale indicated. On the right hand column we represent the dependency on the minimum needlet scale, with all needlet data used beyond this scale. From top to bottom we plot these quantities for the local, equilateral and flattened models respectively.

**Needlet scale dependence.** In order to assess the dependence of our results on the needlet scales, in Fig. 5 we present (in the left hand column) a plot of the best-fit value and the error bar of $f_{NL}$, as we include more needlet scales, up to the maximum scale used in our analysis. On the right hand column we plot the corresponding quantities as we increase the minimum needlet scale. For each case it is necessary to recompute the inverse covariance matrix for the needlet scales under consideration. We present the plots for the local, equilateral and flattened models, noting that the other models considered in this work may be represented as linear combinations of these. The equilateral and flattened models are largely insensitive to the maximum and minimum scale chosen, supporting the observation that we have achieved optimal error bars for each. In the case of the local model there is the possibility that the error bars may shrink slightly with an increased number of needlet scales, as detailed earlier in the section. Nevertheless, the results show the robustness of our results to the choice of scales used.

**D. Trispectrum Constraints**

By comparison with the bispectrum, obtaining constraints on the CMB trispectrum is numerically challenging. Here we briefly review constraints which have appeared in the literature. Desjacques and Seljak found the constraint $\hat{g}_{NL} = [2.35 \pm 2.93] \times 10^5$ using the scale-dependent bias of dark matter haloes in the local model [49]. Smidt et al.
used a pseudo-$C_l$ estimator to obtain $g_{NL}^{loc} = [0.4 \pm 3.9] \times 10^5$. Using a modal decomposition and a suboptimal trispectrum estimator, working up to $l_{\text{max}} = 500$, Regan et al. found $g_{NL}^{loc} = [1.1 \pm 4.9] \times 10^5$ \cite{4, 6}. Recently, Sekiguchi & Sugiyama, using $l_{\text{max}} = 1024$, established that the optimal error bar for the local $g_{NL}$-mode is $2.2 \times 10^5$, finding $g_{NL}^{loc} = [-3.3 \pm 2.2] \times 10^5$. Their analysis implemented the optimal estimator developed in Ref. \cite{4}, using the full pixel-by-pixel inverse covariance matrix. In this paper we work up to $l_{\text{max}} = 1000$, with the pixel-based estimator replaced by a needlet estimator. This has the advantage that, instead of inverting an $\sim$ pixel-by-pixel covariance, we need only invert a $\sim$ needlet estimator, working up to $l$ (see Sekiguchi & Sugiyama, using $l_{\text{max}} = 500$). This only results in a small loss of optimality.

- **Local $g_{NL}$ model.** The local model was discussed in \cite{16}. It gives a trispectrum of the form (24). We find

$$g_{NL}^{loc} = [-2.3 \pm 2.3] \times 10^5 \quad \text{and} \quad \Delta g_{NL}^{loc} = [1.8 \pm 2.2] \times 10^5$$

where (estimated here for the first time) $\Delta g_{NL}^{loc}$ represents the bias due to point sources. Correcting for this bias, the constraint $g_{NL}^{loc} = [-4.1 \pm 2.3] \times 10^5$ is within $\lesssim 5\%$ of the optimal bound and is consistent with the result reported by Sekiguchi & Sugiyama \cite{21}. This represents strong evidence in favour of the accuracy and efficacy of the needlet-based estimator.

The point source constraints reported are calculated using the more accurate model described in the previous section. Using the simpler constant flux model, the point source constraint is calculated to be $\Delta g_{NL}^{loc} = [0.9 \pm 2.2] \times 10^5$. Thus it appears that the constant flux model underestimates the bias due to point sources. However, as we shall see this simple model works well for the other trispectrum models considered, and we will not pursue this interesting issue further in this paper. It is worth noting, however, that the trispectrum constraints appear to show stronger dependency on the presence of point sources than those of the bispectrum. We also consider the dependency of the results on the maximum needlet scale chosen. In Fig. 6, the best-fit and 1σ error bars are plotted as a function of the maximum needlet scale chosen, up until the maximum used in our data analysis. The results show the convergence to the reported values, indicating the robustness of the reported values on the needlet scales chosen.

- **Constant model.** The constant trispectrum was defined in Ref. \cite{6} by analogy with the constant bispectrum. It gives

$$T_{\phi}(k_1, k_2, k_3, k_4) = 24(PP_{\phi}(k_1)PP_{\phi}(k_2)PP_{\phi}(k_3)PP_{\phi}(k_4))^{3/4}. \quad (68)$$

As with the constant bispectrum, features in this model are entirely due to the transfer functions. We find

$$g_{NL}^{\text{const}} = [0.8 \pm 1.8] \times 10^6 \quad \text{and} \quad \Delta g_{NL}^{\text{const}} = [1.0 \pm 1.6] \times 10^6. \quad (69)$$

Correcting for the bias due to point sources this is equivalent to $g_{NL}^{\text{const}} = [-0.2 \pm 1.8] \times 10^6$ and improves on the (corrected) constraint $g_{NL}^{\text{const}} = [1.0 \pm 2.8] \times 10^6$ presented in Ref. \cite{6}. The point source constraint uses the more accurate point source model but is very consistent with the constant flux model which gives

---

$^6$ In these papers, an extra factor of $f_{sky}$ accounting for the sky fraction was erroneously included.
\[ \Delta g_{\text{NL}}^{\text{const}} = [0.8 \pm 1.6] \times 10^6. \] In Fig. 6 we plot the dependency of the results on the (maximum) needlet scale used in the analysis. There appears to be a weak dependency on the maximum scale chosen, but the results clearly support the robust conclusion that the best-fit value lies within \( \sim 1 \sigma \) of zero.

- **Equilateral \( c_1 \) model.** In Refs. [27–32] it was demonstrated that the trispectrum for single-field inflation models with nontrivial kinetic terms receives its dominant contribution from a combination of three trispectra \( T_{s_1,s_2,s_3} \) generated by scalar exchange, and three trispectra \( T_{c_1,c_2,c_3} \) generated by contact interactions. As explained in Ref. [33], the \( c_1 \)-type contact-interaction trispectrum is strongly correlated with most of the other shapes. Helpfully, it can be described by a simple diagonal-free formula, for which

\[
T_{c_1}(k_1, k_2, k_3, k_4) = \frac{24A_{\Phi}^3}{k_1 k_2 k_3 k_4 (\sum_i k_i / 4)^5}.
\]  

(70)

We find the constraints

\[
g_{\text{NL}}^{c_1} = [0.8 \pm 2.9] \times 10^6 \quad \text{and} \quad \Delta g_{\text{NL}}^{c_1} = [1.6 \pm 2.5] \times 10^6.
\]  

(71)

The constraint after correction for biasing is \( g_{\text{NL}}^{c_1} = [-0.8 \pm 2.9] \times 10^6 \). This is again consistent with the (corrected) result of Ref. [34], which found \( g_{\text{NL}}^{c_1} = [-2.4 \pm 5.8] \times 10^6 \). As for the constant model, the constraint on the point sources is largely insensitive to the model used with the constant flux model giving the constraint \( \Delta g_{\text{NL}}^{c_1} = [1.2 \pm 2.5] \times 10^6 \). In addition, the plot of the dependency on the maximum needlet scale in Fig. 6 further supports the conclusion that the best-fit value lies within \( \sim 1 \sigma \) of zero.

- **Local \( \tau_{\text{NL}} \) model.** The local model [56] also generates a trispectrum in the \( \tau_{\text{NL}} \)-mode, which gives \( \tau_{\text{NL}}^{\text{loc}} = (6f_{\text{NL}}^{\text{loc}}/5)^2 \). In models with more contributions to the curvature perturbation this is softened to an inequality \( \tau_{\text{NL}}^{\text{loc}} \gg (6f_{\text{NL}}^{\text{loc}}/5)^2 \) [53–55]. Therefore, simultaneous detections of \( \tau_{\text{NL}}^{\text{loc}} \) and \( f_{\text{NL}}^{\text{loc}} \) would provide an opportunity to probe the microphysics of the inflationary era.

Unfortunately, estimating \( \tau_{\text{NL}}^{\text{loc}} \) is a challenging undertaking. Ref. [34] derived the estimator \( \hat{\tau}_{\text{NL}}^{\text{loc}} = \mathcal{E}_{\tau_{\text{NL}}}/\langle \mathcal{E}_{\tau_{\text{NL}}} \rangle \), where

\[
\mathcal{E}_{\tau_{\text{NL}}} = 3 \sum_{l,m} (-1)^M \mathcal{P}_{l_1 l_2}^{l_1 l_2} (L) \mathcal{G}_{m_1 m_2}^{l_1 l_2} \mathcal{G}_{m_3 m_4}^{l_3 l_4} M \times \left( \prod_{i=1}^4 a_{i,m} - (\bar{a}_{i,m} \bar{a}_{i,m} \bar{a}_{i,m} \bar{a}_{i,m}) + 5 \text{perms} \right) \]  

\[
\langle \mathcal{E}_{\tau_{\text{NL}}} \rangle \approx 3 \sum_{l,L} \mathcal{P}_{l_1 l_2}^{l_1 l_2} (L) \hat{h}_{l_1 l_2 L} \hat{h}_{l_3 l_4 L} \left( \frac{\mathcal{P}_{l_1 l_2}^{l_1 l_2} (L) \hat{h}_{l_1 l_2 L} \hat{h}_{l_3 l_4 L}}{2L + 1} + \sum_{L'} (-1)^{L+L'} \left\{ \frac{l_1}{l_4} \frac{l_2}{l_3} L L' \mathcal{P}_{l_1 l_2}^{l_1 l_2} (L') \hat{h}_{l_1 l_2 L} \hat{h}_{l_3 l_4 L} \right\} \right) + \sum_{L'} (-1)^{L+L'} \left\{ \frac{l_1}{l_3} \frac{l_2}{l_4} L L' \mathcal{P}_{l_1 l_2}^{l_1 l_2} (L') \hat{h}_{l_1 l_2 L} \hat{h}_{l_3 l_4 L} \right\},
\]  

(72)

where \( a_{i,m} = (C^{-1}a)_{i,m} \) are the inverse-covariance weighted spherical harmonics and

\[
\hat{h}_{l_1 l_2 L} \equiv \sqrt{\frac{\prod_{i=1}^3 (2l_i + 1)}{4\pi}} \left( \begin{array}{cc} 1 & 1 \end{array} \right)_{L}.
\]  

(73)

We have expressed \( \langle \mathcal{E}_{\tau_{\text{NL}}} \rangle \) using the approximation of a diagonal covariance matrix. Unfortunately, the presence of the 6j symbols \( \{ \ldots \} \) means that the computation of \( \langle \mathcal{E}_{\tau_{\text{NL}}} \rangle \) is prohibitive and therefore some approximations are required. For example, it is an accurate approximation to restrict the calculation to \( L \lesssim 100 \) and neglect the effect of the 6j symbols [56].

However, the needlet estimator [51] obviates this by removing the necessity to calculate the 6j symbols explicitly. Nevertheless, the \( \tau_{\text{NL}} \) model still represents a formidable numerical challenge due to the presence of two line-of-sight integrals in (34).

To make progress, we use the observation of Pearson et al. [23] that Eq. (30) represents an accurate approximation to the \( \tau_{\text{NL}} \) trispectrum shape. In this paper we employ it for the calculation of expectation values of the quartic needlet statistic, Eq. (45). We note that a similar approximation could be applied to the trispectrum generated by cosmic strings, or due to lensing.
Alternative approaches are possible. A modulation-based estimator was developed by Pearson et al. [28] and was applied to Planck data for the Planck2013 data release [57]. This modulation-based estimator is similar to Eq. (72) with (39) used to approximate the τNL-mode trispectrum. That is,

$$\mathcal{E}_{\text{mod}}^{\tau_{NL}} = 12 \sum_L C_L^2 \sum_M \left( |f_{LM} - \langle f_{LM} \rangle|^2 - \langle |f_{LM}^G - \langle f_{LM}^G \rangle|^2 \rangle \right),$$  \hspace{1cm} (75)$$

where

$$f_{LM} = \int d^2 n \ Y_{LM}^* (\hat{n}) \sum_{l_1 m_1} \hat{a}_{l_1 m_1} Y_{l_1 m_1} (\hat{n}) \sum_{l_2 m_2} C_{l_2} \hat{a}_{l_2 m_2} Y_{l_2 m_2} (\hat{n}).$$  \hspace{1cm} (76)$$

Applying the needlet estimator [51] gives constraints for the amplitude and bias due to point sources, $\hat{\tau}_{NL}(L) = 3020 [57]$. Although not strictly correct, we expect that this will yield qualitatively accurate results. That is, $\hat{\tau}_{NL}(L)$ estimators as uncorrelated, the posterior distribution $P(\tau_{NL}; \{\hat{\tau}_{NL}(L)\})$ is given by the product of inverse Gamma functions [57 60]

$$P(\tau_{NL}; \{\hat{\tau}_{NL}(L)\}) \propto \prod_{L=\text{min}}^{L=\text{max}} f \left[ x(L)^{-1}; (2L - 1)/2, (2L + 1)/2 \right],$$  \hspace{1cm} (80)$$

where the inverse Gamma distribution $f(x; \alpha, \beta)$ with shape parameter $\alpha$ and scale parameter $\beta$ is defined by

$$f(x; \alpha, \beta) = \frac{\beta^\alpha}{\Gamma(\alpha)} x^{-\alpha-1} e^{-\beta/x}.$$  \hspace{1cm} (81)$$

In this paper we wish to work with the needlet-based estimator. Therefore we approximate the quantity $\hat{\tau}_{NL}(L)$ by our estimate $\hat{\tau}_{NL}$ for all $L$. Although not strictly correct, we expect that this will yield qualitatively accurate constraints. To deduce $N_L$ we utilise the expression $\sigma(\tau_{NL})^{-2} \approx \sum_L (2L + 1) C_L^2 / N_L^2$, and note that it represents white noise, and therefore is independent of $L$.

The resulting constraint is

$$\tau_{NL}^{\text{loc}} < 22000$$  \hspace{1cm} (82)$$

which compares with the Planck2013 error bar $\tau_{NL}^{\text{loc}} < 2800 [57]$.
V. CONCLUSIONS

In this paper we have coupled the successful ‘modal’ or partial-wave method for non-separable bi- and tri-spectra to a needlet-based estimator. This extends the approach of Ref. [8] in which the partial-wave method was coupled to a wavelet-based estimator. The key step in this approach is the introduction of ‘change-of-basis’ matrices \( \langle N_{i,j} \rangle \) and \( \langle N_{i,j}^T \rangle \). In principle, a variant of this method can be used to couple the partial-wave decomposition to any desired estimator.

The needlet- and wavelet-based estimators are efficient because they require inversion of a covariance matrix of order \( \sim 10^3 \times 10^3 \) rather than the full pixel-by-pixel covariance matrix of order \( \sim 10^6 \times 10^6 \). Despite this reduced computational burden, our comparison with the 9-year WMAP data demonstrates that these estimators are close (within \( \lesssim 5\%–10\% \)) to optimal. Both the needlet- and wavelet-based estimators are efficient detectors of point sources, but our results suggest that the needlet-based estimator is most sensitive.

We have used our approach to construct the first needlet-based estimator for the trispectrum. As a by-product, this estimator avoids the general (expensive) requirement to explicitly calculate Wigner-6j symbols. For the class of diagonal-free trispectra (that is, those which depend only on the multipoles \( l_i \) in the harmonic decomposition of the CMB) we employ the partial-wave expansion approach developed in Refs. [4, 6]. However, the estimator can equally well be applied to trispectra which are not diagonal-free. As an example, we have used it to constrain the local \( \tau_{NL} \)-shape trispectrum. Alternative uses could include searches for trispectra generated by cosmic strings or lensing.

We have tabulated constraints on the local, DBI, equilateral, constant, orthogonal and flattened bispectra. For each of these models we provide estimates of the contamination due to point sources. We have also studied the frequency-dependence of our results, for which the constraints on the orthogonal model are particularly interesting. While the WMAP team did not suggest a strong signal for this model in the 9-year data \( \sim 2.5\sigma \), their analysis suggested a much stronger W-band signature \( \sim 2.9\sigma \) compared to the V-band \( \sim 1.1\sigma \). Using the needlet-based estimator we have shown that all models, including the orthogonal bispectrum, are essentially frequency independent. The expected point-source contribution shows a mild frequency dependence, at the level of a fraction of an error bar.

We also tabulate constraints for a selection of trispectrum shapes, including the local \( g_{NL} \)-shape, constant, and \( c_1 \) equilateral trispectra. The \( c_1 \) model is representative of certain inflationary models with non-canonical kinetic terms. All three models are ‘diagonal-free’, which allows a decomposition into partial waves. Our constraints on \( g_{NL} \) are close to optimal. Finally, we constrain the local \( \tau_{NL} \)-shape trispectrum. This is not diagonal-free, but can be modelled using an accurate separable approximation similar to that employed by Pearson et al. [28]. All of these constraints show that the CMB does not deviate from the standard paradigm of a Gaussian primordial fluctuation, to both three-point and four-point order. In addition we have computed, for the first time, the effect of point sources on each of these trispectrum models. As with the bispectrum, each model shows only mild bias due to the presence of unresolved point sources.

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