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Constraining the dark fluid

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Cosmological observations are normally fit under the assumption that the dark sector can be decomposed into dark matter and dark energy components. However, as long as the probes remain purely gravitational, there is no unique decomposition and observations can only constrain a single dark fluid; this is known as the dark degeneracy. We use observations to directly constrain this dark fluid in a model-independent way, demonstrating, in particular, that the data cannot be fit by a dark fluid with a single constant equation of state. Parametrizing the dark fluid equation of state by a variety of polynomials in the scale factor $a$, we use current kinematical data to constrain the parameters. While the simplest interpretation of the dark fluid remains that it is comprised of separate dark matter and cosmological constant contributions, our results cover other model types including unified dark energy/matter scenarios.

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I. INTRODUCTION

The standard cosmological model appeals to two separate dark components—dark matter and dark energy—and the usual application of observational constraints places limits on each of these. However, at present these two components have only been detected through their gravitational influence, and these measurements do not provide enough information to permit a unique decomposition into these components. Rather, it is a model assumption that the two components are separate. This point was first made in Ref. [1] and specific consequences explored in Refs. [2,3]. Reference [4] extended it to coupled models and named it the dark degeneracy.

This degeneracy is extremely general. One can write

$$G_{\mu\nu} - \kappa T^{\text{visible}}_{\mu\nu} = \kappa T^\text{dark}_{\mu\nu},$$

where $G_{\mu\nu}$ is the Einstein tensor, $T_{\mu\nu}$ the energy-momentum tensor, and $\kappa$ the gravitational coupling. Any gravitational probe of the dark sector amounts to evaluating the left-hand side of this equation, and interpreting the nonzero result as evidence for the dark sector. Having obtained the dark sector energy-momentum tensor this way, such observations can offer no guidance on how that tensor might be split among different dark components.\(^\dagger\)

Although the degeneracy holds even for structure formation probes (both linear and nonlinear) of the dark sector, we will focus here only on kinematical probes, i.e. those referring to the homogeneous and isotropic background cosmology. A complete dark sector description is then given by the total dark sector energy density and its equation of state $w_{\text{dark}}$, the latter determining the evolution of the former. This enables a simple analysis. To include structure formation data, while retaining statistical homogeneity, one would also need to consider at least the dark sector sound speed and perhaps also anisotropic stress [1,4], and one might expect that structure formation observations would end up mostly constraining their form rather than imposing further upon $w_{\text{dark}}$.

As a simple example [1], in the standard cosmological model (SCM) the redshift evolution of the total dark sector equation of state

$$w_{\text{dark}} = \frac{\sum \rho_i w_i}{\sum \rho_i},$$

(where $i$ runs over the dark components) is given by

$$w_{\text{dark}}(z) = -\frac{1 - \Omega_{m,0}}{1 - \Omega_{m,0} + (\Omega_{m,0} - \Omega_{h,0})(1 + z)^3},$$

$$\approx -\frac{1}{1 + 0.31(1 + z)^3}.\quad (4)$$

Here $\Omega_m$ and $\Omega_h$ are the total matter density parameter and the baryon density parameter, and the subscript 0 indicates present value. Equation (4) follows from inserting the values $\Omega_{m,0} = 0.274$ and $\Omega_{h,0} = 0.046$ obtained from current data compilations [6].

Inclusion of a single dark energy component with this equation of state evolution would give the same observational predictions as the standard cosmology. Indeed, once one allows the dark energy equation of state to evolve arbitrarily, one cannot say anything from observations about the dark matter density $\Omega_{dm}$ as its effects can always be reinterpreted as due to the dark energy. Analyses which appear to measure $\Omega_{dm}$ accurately only manage to do so
because the dark energy parametrization adopted is not general enough to be able to mimic the form of Eq. (3).

This degeneracy is perfect. All we can say in a model-independent way is that the present total dark sector density is about 0.95, and that its equation of state is constrained to evolve in a particular way from an early-time value at or near zero to arrive at its present value of \( w_{\text{dark}}(z = 0) \approx -0.8 \). Our aim in this paper is to more precisely quantify these constraints, by considering general dark sector models that do not include a pure cold dark matter (CDM) component.

II. MODELS AND DATA

Having set up this nonstandard framework for analyzing the dark sector, our analysis procedure is standard and straightforward.

A. Models

In order to impose constraints on the dark fluid, we need to employ a parametrization of its equation of state. Henceforth we drop the subscript “dark,” using \( w \) throughout as the total dark sector equation of state. As we wish to reach high redshift, we parametrize \( w \) as a function of scale factor \( a \), which has the bounded domain \( 0 < a \leq 1 \). We simply expand this as a power series in \( a \) at the present, which we find to be sufficient. At linear order this is the well-known Chevallier-Polarski-Linder (CPL) parametrization \( w = w_0 + (1 - a)w_1 \) [7], normally applied to the dark energy alone but here referring to the combined dark sector. To general order this expression was given, again for the dark energy alone, in Ref. [8], which in actual calculation considered the linear and quadratic versions. As we are demanding that our parametrization describe the entire dark sector, we will explore up to cubic order. Our models are hence

\[
w(a) = \sum_{n=0}^{N} w_n (1 - a)^n \tag{5}
\]

for different choices of \( N \).

As we will see, the data strongly demand that \( w(a) \) is close to zero as \( a \to 0 \), i.e. the dark sector is required to behave as dark matter at early times (note that this is true even without inclusion of any structure formation data). Accordingly we will also consider the same expansions supplemented with the additional constraint \( w(a = 0) = 0 \) which fixes their highest-order term as a function of the others, and with the combined constraints \( w(a = 0) = 0 \) and \( dw/da|_{a=0} = 0 \). We will call these the “constrained” and “doubly-constrained” expansions, respectively. The former can be used from linear order upward, and the latter from quadratic upward.

In all cases we choose priors on the expansion coefficients which are wide enough that the outcome is determined entirely by the data and not the prior.

The standard rulers measured by the cosmic microwave background (CMB) and baryon acoustic oscillations (BAO) are all fixed by the sound horizon at decoupling (which we fix to be \( z_{\text{dec}} = 1089 \)), which is dependent on the baryon density. The standard rulers are all distance ratios independent of \( H_0 \), and the supernovae make no measurement of the Hubble parameter \( H_0 \) since it is degenerate with the unknown absolute normalization over which we marginalize. As our data compilation does not constrain \( H_0 \), it is not able to give an accurate constraint on the total dark sector energy density. However the physical baryon density \( \Omega_b h^2 \) is accurately measured to the usual value, and so if supplemented with a direct determination of \( H_0 \), we would find the expected total dark sector energy density \( \Omega_{\text{dark}} \approx 0.95 \). In our analysis we allow \( \Omega_b h^2 \) and \( H_0 \) to vary, but constrain them using other data sets, and marginalize over them, in effect marginalizing over the total dark sector energy density.

In light of the above, when we quote model parameter counts they are of the dark sector equation of state, and do not include the total dark sector energy density. For the general dark sector models, we quote the number of parameters specifying \( w(a) \). For \( \Lambda \)CDM, the equivalent parameter is the relative amount of dark matter and dark energy at present [equivalently, the coefficient of the \((1 + z)^3 \) term in Eq. (4)].

B. Data

We use a fairly typical combination of kinematical data to constrain our models. Standard candle data come from supernova type Ia (SNIa) luminosity distances, for which we use the cut Union supernova sample [9] (with systematic errors included), and standard ruler data come from the angular positions of the CMB [10] and BAO peaks [11]. Note that Ref. [10] give constraints on the scaled distance to recombination \( R \) and the angular scale of the sound horizon \( l_a \). These are defined to be

\[
R = \sqrt{\frac{\Omega_m H_0^2 r(z_{\text{CMB}})}{\Omega_b h^2}}, \quad l_a = \frac{\pi r(z_{\text{CMB}})}{r_s(z_{\text{CMB}})}. \tag{6}
\]

Since \( R \) is scaled by the physical matter density, and so makes assumptions about the separability of the dark matter and dark energy, we ignore it in this work. We use only the constraints on \( l_a \), as well as those on \( \Omega_b h^2 \) and the correlations between the two. This still assumes that the sound speed of the dark component at high redshift is small, in order to avoid an early integrated Sachs-Wolfe effect shifting the peak position. We also include the SHOES (Supernovae and \( H_0 \) for the Equation of State) measurement of the Hubble parameter today, \( H_0 = 74.2 \pm 3.6 \text{ km s}^{-1} \text{ Mpc}^{-1} \) [12].
III. RESULTS

Table I shows the number of adjustable parameters and best-fit chi squared for our various models, including ΛCDM for comparison. The total number of data points is 313 (308 SNIa, 2 BAO, 2 CMB, and 1 from the SHOES project), but correlations between the data points make it difficult to state the number of independent data points, and so the number of degrees of freedom. We can say that the number of degrees of freedom is, at most, 311 minus the number of dark sector parameters, meaning that the data are an acceptable fit to all the models, except the constant \( w \) model, if the correlations are small.

The corresponding \( w(a) \) curves of the best-fitting version of each model are shown in Fig. 1. The immediate conclusions from these are as follows:

1. ΛCDM, as expected, does a good job of fitting the data, bettered only by other models with more dark sector parameters. For our data the best-fit \( \Omega_m \) is 0.26 ± 0.02. This agrees well with the result of Komatsu et al. [6], with somewhat larger uncertainty as less data are being used.

2. Even the best-fit version of the constant \( w \) model is a very poor fit. The dark sector has not had a constant equation of state throughout its evolution.

3. The full four-parameter cubic does not significantly improve the fit over the three-parameter quadratic, indicating that three-parameter models saturate the constraining power of the data.

4. All the models have \( w(a = 0) \) at or very close to zero, enforced entirely by the data. This indicates that the full phenomenology can be captured using the constrained versions of the expansion, reducing the variable parameter set by at least one.

5. The doubly-constrained quadratic [i.e. simply \( w(a) = w_0 a^2 \)] gives a tolerable one-parameter fit to the data, though not quite as good as the ΛCDM fit. By contrast, the single-parameter constrained linear fit is a poor fit to the data when compared to the ΛCDM fit, which has the same number of parameters (though the general CPL model can acceptably fit it by overshooting to \( w > 0 \) at early times).

6. In terms of giving good fits to the data for economical numbers of parameters, apart from ΛCDM the two-parameter constrained quadratic and doubly-constrained cubic fits are the most appealing models.

More relevant than the best-fit parameters are the ranges of parameter values permitted by the data. As all constant \( w \) models are ruled out, we show in Figs. 2 and 3 the constraints on the parameters of the CPL and quadratic

![FIG. 1 (color online).](image1)

The best-fit \( w(a) \) for our various models. Note that the approach to \( w = 0 \) at \( a = 0 \) is determined entirely by the data in the unconstrained cases, while being enforced in the constrained models.

![FIG. 2 (color online).](image2)

Parameter constraints on the linear (CPL) parametrization. The constrained models lie on the line \( w_1 = -w_0 \), shown as the solid (blue) line on the \( w_0, w_1 \) plot.
parametrizations, and in Fig. 4 we show the constraints on the constrained quadratic model, which forces $w(a = 0) = 0$.

For illustrative purposes, Fig. 5 shows 400 quadratic $w(a)$ curves drawn randomly from the Markov chain. They are shaded so that the likelihood increases from blue (darker) to red (lighter). We can see that the high-redshift region near $a = 0$ is strongly constrained and requires $w = 0$, while the value of the total equation of state parameter today, $w_0 = w(a = 1)$, is only very weakly constrained by the data sets used in this work.\footnote{As we were completing this work, Mortonson et al. [13] published a paper considering this specific point in much more detail. This point had also previously been noted in Ref. [14].} Because of the integrated nature of the distance constraints on $w$, curves that oscillate around the best-fit incur only a small penalty. This becomes more problematic when going to higher order in power law expansions since then more oscillations become possible. As the oscillations have to average out, the expansion parameters are highly corre-

\begin{figure}[h]
\centering
\includegraphics[width=0.5\textwidth]{fig3}
\caption{(color online). Parameter constraints on the quadratic parametrization. Here $w_b = w_0 + w_1 + w_2$, which is the combination which is held at zero in the constrained quadratic case.}
\end{figure}

\begin{figure}[h]
\centering
\includegraphics[width=0.5\textwidth]{fig4}
\caption{(color online). Parameter constraints on the constrained quadratic parametrization, where $w(a = 0)$ is set to zero. The doubly-constrained models lie on the line $w_1 = -2w_0$, shown as the solid (blue) line on the $w_0, w_1$ plot.}
\end{figure}
lated and not really independent, which can already be seen for \( w_0 \) and \( w_1 \) in the quadratic case in Fig. 3.

We also carried out a different analysis where the equation of state \( w \) is allowed to take different values in binned regions of scale factor \( a \), for simplicity taken to be linearly spaced with 10 or 20 bins. A principal component analysis showed that three modes were well measured (\( \sigma < 0.1 \)), supporting the conclusions above. This analysis also showed that the best measured mode was peaked in the highest-redshift bin.

IV. CONCLUSIONS

Because of the dark degeneracy, there is no unique split into dark matter and dark energy. For this reason, we considered in this paper the total dark sector equation of state. We parametrized it with polynomial expansions in the scale factor \( a \) and used type Ia supernovae, baryon acoustic oscillations, and the CMB peak position to find constraints on the expansion parameters.

The strongest constraints come at very high redshift, from the CMB and BAO measurements of the sound horizon at decoupling. There the dark fluid must evolve with an equation of state close to zero, to recover the correct angular scale of the acoustic oscillations. At low redshift the constraints from SNIa and BAO are weaker, but require a negative pressure fluid with \( w_{\text{dark}} \approx -0.8 \).

We found that \( \Lambda \)CDM gave the best one-parameter fit to current data, bettered only by other models with at least two parameters such as the doubly-constrained cubic expansion. However, none did very much better than \( \Lambda \)CDM. Accordingly, \( \Lambda \)CDM remains the most compelling interpretation of present data, despite the dark degeneracy. Nevertheless our polynomial fits indicate the constraints that can be applied to more general types of dark sector model.

One could speculate about how future measurements of the same general type might tighten our constraints, but as remarked in the introduction they cannot address the issue of separability of the dark sector into components. Rather, to defeat the dark degeneracy what is needed are non-gravitational probes of the sector, for instance direct detection of dark matter particles at accelerators or in underground experiments [4]. Such detections would immediately move such particles from the dark sector to the “known” sector, removing them from the dark sector degeneracy.

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